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MIMO Backscatter Channel and Data Transmission Measurements

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Abstract—Backscatter modulation is more and more establishing itself as an approach for low-cost and low-power data transmission. Combined with multi-antenna techniques and channel state information (CSI) an enhancement of range, reliability or spectral efficiency is achieved. However, there has been few literature about gaining CSI for the individual sub-channels of forward and backward link. The contribution at hand deals with multi-antenna backscatter measurements with up to two scatter antennas and two receive antennas, in order to investigate the backscatter channel and the data transmission within a multi-path environment at 5.8 GHz. The paper provides a method for determining the individual sub-channels and investigates the multi-antenna backscatter channel capacity and symbol error ratios for backscatter spatial multiplexing using CSI.

I. INTRODUCTION

Radio frequency identification (RFID) systems have spread widely into the daily life. Such systems usually employ the principle of backscatter modulation, which is based on transmitting data by modulating the scattering behaviour of a passive (battery-less) or semi-passive (battery-assisted) transponder/tag being interrogated by a reader [1]. Besides its original task of the identification of goods, this technology is used as well in new fields like the internet of things [2], sensing applications, e.g., for medical purposes like neurorecording [3] or in wireless sensor networks [4]. In these fields low-cost and low-power devices are incorporated, demanding increased transponder communication capabilities.

While multiple-input multiple-output (MIMO) techniques in classical communication systems are well established, such systems usually employ the principle of backscatter modulation, which is based on transmitting data by modulating the scattering behaviour of a passive (battery-less) or semi-passive (battery-assisted) transponder/tag being interrogated by a reader [1]. Besides its original task of the identification of goods, this technology is used as well in new fields like the internet of things [2], sensing applications, e.g., for medical purposes like neurorecording [3] or in wireless sensor networks [4]. In these fields low-cost and low-power devices are incorporated, demanding increased transponder communication capabilities.

While multiple-input multiple-output (MIMO) techniques in classical communication systems are well established, e.g., WiFi or Long-Term Evolution standards are well established, the use of multiple antennas in backscatter systems for transmission or reception at the reader and scattering or reception at the transponder is rather new. Multi-antenna backscatter systems may incorporate M, L and N antennas at the transmitter (TX), the tag and the receiver (RX), respectively, and span a forward and a backward channel [5]. First concepts for this emerged in 2001 [6], followed by more intensified research in recent years adapting transmission techniques like, e.g., space time coding at the tag end [7].

Wireless MIMO communication systems heavily depend on the properties of the propagation channel in order to achieve the intended enhancement of range, reliability or spectral efficiency. This dependence is even more crucial for backscatter based systems due to their dyadic channel structure, in which fading effects are more severe due to the keyhole nature of

![Fig. 1. Scheme of the measurement setup](image-url)

The setup comprises a vector network analyzer (VNA) and a prototype transponder with two scattering antennas (see Fig. 1). The backscatter channel and the transponder data transmission within a multi-path environment are investigated...
at 5.8 GHz for a multitude of channel realizations. The paper provides results for the individual sub-channels and investigates the backscatter channel capacity and symbol error ratios for backscatter spatial multiplexing using CSI. Comparable results have not been shown in literature before. The paper is organized as follows. Sec. II introduces the reader and transponder hardware and describes the measurement scenario. Sec. III presents the signal processing regarding channel estimation, structure of the backscatter signals, capacity calculation and payload detection. Sec. IV discusses the measurement results in terms of channels, capacity and symbol error ratios. The paper is concluded in Sec. V.

II. MEASUREMENT SETUP

The measurement setup, depicted as a scheme in Fig. 1, is based on a VNA (Rohde & Schwarz ZVA8), which is utilized as a multi-channel vector signal analyzer. The setup constitutes a $1 \times 2 \times 2$ backscatter system with 1 TX/RX antenna, using two VNA ports, i.e., two antennas for reception, one of which is used as well for transmitting the continuous wave (CW) signal at 5.8 GHz, being backscatter modulated by the two-antenna transponder. This leads to a 4-port scattering matrix $R$ incorporating the narrowband channel coefficients $R_{xx}$ being terminated by the scattering coefficients $\tilde{\Gamma}_x$, as seen from the tag antenna ports ($l$ is the scattering port number). For all antennas, monopoles are used. The resulting time-varying 2-port scattering matrix $S$ is measured over time and post-processed in MATLAB ($S_{22}$ is not obtained). By this means the data transmission on the backscatter link can be assessed. No modulated reader query signal is necessary, since an experimental transponder is used, triggered via cables. The transponder comprises two monopole antennas connected to two backscatter modulators (asymmetric 4-QAM), realized with open ended microstrip transmission lines of different lengths, connected to a SP8T microwave switch (Hittite HMC321LP4), controlled via TTL with a logic signal output module (Rigol DG-POD-A) [16]. Fig. 2 depicts one of the manufactured modulators. The positioning of modulators and tag antennas relative to the reader antennas is shown in Fig. 3.

The setup is established within a shielded room with some furniture (see Fig. 4), resulting in a multi-path environment incorporating non-line of sight (NLOS) and line-of-sight (LOS) propagation paths. By positioning the transponder on top of a stepper motor slide, various channel realization are obtained.

III. SIGNAL PROCESSING

A. Channel Reconstruction Algorithm

The channel matrix of a $1 \times 2 \times 2$ system with 1 TX/RX antenna is definable by a reciprocal 4-port scattering matrix $R$ (see Fig. 1). By terminating two ports of $R$ with the transponder reflection loads, the measurable 2-port-scattering matrix is

$$S = \begin{pmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{pmatrix} = \begin{pmatrix} R_{11} & R_{12} \\ R_{21} & R_{22} \end{pmatrix} + \begin{pmatrix} R_{13} & R_{14} \\ R_{23} & R_{24} \end{pmatrix}^{-1} \begin{pmatrix} R_{33} & R_{34} \\ R_{43} & R_{44} \end{pmatrix}^{-1} \begin{pmatrix} R_{31} & R_{32} \\ R_{41} & R_{42} \end{pmatrix}. $$

In order to determine the desired channel information, one out of three loads of the transponder signaling matrix is used as a known termination $\tilde{\Gamma}_l$ for each tag antenna at one time, while the other tag antenna is terminated with the reference impedance of 50 Ω ($\tilde{\Gamma}_0 \approx 0$). By this means (1) simplifies to

$$S_{nm,a,b,c} = R_{nm} + \frac{R_{tn} R_{nl} \tilde{\Gamma}_{l,a,b,c}}{1 - R_{tl} \tilde{\Gamma}_{l,a,b,c}}. $$

where $m$ denotes the transmitting and $n$ the receiving port number. By measuring $S$ in $L \cdot 3 = 2 \cdot 3 = 6$ transponder states, the relevant parts of $R$ can be calculated in accordance to the three-term error model (see [16], [17]), comparable to characterizing a multi-port scattering matrix with a VNA using a reduced number of ports. Consequently, a corresponding training symbol sequence is scattered by the transponder as a preamble prior to the payload symbols.

B. Structure of the Data Signal

For each position of the stepper motor slide, i.e., for each distinct static channel realization, spatially multiplexed random payload data is scattered, headed by a preamble. The preamble consists of 1 symbol used for triggering purposes, 12 constant symbols utilized for noise estimation and 24 training symbols. The latter comprises 8 symbols for channel estimation (6 are used, see Sec. III-A) and $4^{L-2} = 16$ reference symbols used for data detection (both modulators scatter at the same time in all combinations appearing like a 16-QAM, cp.
Sec. III-D2). Fig. 5 and Fig. 6 show, exemplarily, the measured scattering parameter $S_{11}$ over time and as the corresponding constellation diagram for one channel realization.

**C. Channel Capacity**

The capacity of the backscatter link is affected by both the forward and the backward channel [6]. The forward channel accounts for power delivery to the tag antennas for energy harvesting and backscattering, whereas the backward channel depends on a rich scattering scenario to achieve significant capacity. The channel capacity is calculated as follows [18]:

$$C = \log_2(\det[1 + \rho H_f H_f^H Q H_b^H H_b^H])$$

with $Q = E[xx^H]$. 

$$H_f = \begin{pmatrix} R_{31} \\ R_{41} \end{pmatrix}$$

and $H_b = \begin{pmatrix} R_{13} & R_{14} \\ R_{23} & R_{24} \end{pmatrix}$ are the forward and backward channel matrices, i.e., the respective sub-matrices of $R$. The signal-to-noise ratio (SNR) is denoted by $\rho$, $x$ is the reader CW transmit signal, $H_f$ is the Hermitian transpose operator and $E$ is the expectation. The magnitude of the CW signal and the backscatter symbols is supposed to be unity.

**D. Detection of the Transponder Payload Data**

1) **Zero Forcing:** In order to detect the backscatter payload data in MATLAB post-processing, a zero forcing equalizer was implemented (modified from [9]). By this means both symbol streams are separated from each other using CSI gained from the preamble. An independent symbol decision is made and the symbol error ratio (SER) is determined.

2) **Reference Symbol Based Method:** Another data detection method is based on comparing the received payload signals to the 16 reference symbols of the preamble as a combined ”16-QAM” stream. Both RX-antennas are used for a SNR-weighted combined decision. Since for distinct channel realizations some constellation points may overlap, detection is not possible in any case resulting in a degraded SER performance.

**IV. MEASUREMENT RESULTS**

**A. Channel**

Fig. 7 shows the magnitude of the channel coefficients calculated as described in Sec. III-A for a multitude of channel realizations in a spatial grid of $\lambda/4$. Additionally, the LOS share of $R_{31}$ is estimated by using far field free space path loss assumptions for comparison. Due to the multi-path environment, an intense small scale fading based on multiple NLOS propagation paths superimposed by the LOS path is present, which may be modeled by a Rician distribution with varying power in the LOS path. Fig. 8 additionally shows the corresponding cumulative distribution function (CDF), illustrating that all coefficients are similarly distributed.

**B. Channel Capacity**

Fig. 9 depicts the channel capacity as calculated using (3) and measured CSI from Sec. IV-A for different antenna scenarios (all channels normalized by the averaged magnitude of all coefficients involved in order to obtain a mean SNR $\rho = 10$ dB). For comparison, Fig. 10 shows the simulated capacity for these scenarios, when Rayleigh fading (solely NLOS share) is assumed (10000 realizations, see [18]). More antennas on each side provide more capacity, whereas, however, more transponder antennas are superior to, e.g., more RX-antennas, due to the transponder being a link between forward and backward channel similar to a keyhole.

**C. Symbol Error Ratios for Spatial Multiplexing**

For each channel realization, backscatter transmission of two spatially multiplexed symbol streams is assessed. Fig. 11 verifies the feasibility of separating both streams (unequal SNR) with zero forcing for an exemplary measurement. The constellations slightly differ from each other due to the modulator fabrication process. Fig. 12 compares both methods from Sec. III-D for two tag scattering antennas ($L = 2$) in addition to one stream with one scattering antenna ($L = 1$) in terms...
of the SER. Obviously, one stream shows best performance compared to two streams sharing the spectrum. Using CSI for zero forcing outperforms the reference symbol based method.

V. CONCLUSION

In this contribution multi-antenna backscatter measurements at 5.8 GHz with up to two scatter and two receive antennas in a multi-path environment are presented. Results for the individual sub-channels of forward and backward link in various realizations are shown, allowing for an investigation of the backscatter link capacity. Additionally, the symbol error ratios for spatial multiplexing backscatter transmission are assessed.

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